

# Parameter Estimation in Probabilistic Knowledge Structures – Step by Step

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## Abstract

This vignette provides some details about the parameter estimation procedures implemented in the pks package.

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Doignon and Falmagne (1999) describe two probabilistic models frequently used in applications of the theory of knowledge structures: the basic local independence model (BLIM) and the simple learning model (SLM). This vignette provides some details about the parameter estimation procedures implemented in the pks package, which are an adaptation of the expectation-maximization algorithm. Section 1 contains methods for the BLIM. The results are taken from Heller and Wickelmaier (2013) and are repeated here (with intermediate steps) in order to motivate the analogous derivations for the SLM in Section 2.

## 1. The basic local independence model

### 1.1. Likelihood and log-likelihood

Let  $R \in \mathcal{R}$  be a response pattern,  $K \in \mathcal{K}$  be a knowledge state, and  $q \in Q$  be an item. Let  $N_R$  be the observed frequency of response pattern  $R$ . For the BLIM, the parameter vector  $\theta = (\beta, \eta, \pi)$  consists of (vectors of) careless error, lucky guess, and state probabilities. The likelihood of  $\theta$  given all observed response patterns has the multinomial form

$$L(\theta) = \prod_R P(R)^{N_R} = \prod_R \left( \sum_K P(R, K) \right)^{N_R}. \quad (1)$$

Let  $M_{RK}$  denote the unobservable frequency of pattern  $R$  resulting from state  $K$ . Then the likelihood simplifies to

$$L(\theta) = \prod_R \prod_K P(R, K)^{M_{RK}} \quad (2)$$

$$= \prod_R \prod_K (P(R | K) \cdot P(K))^{M_{RK}} \quad (3)$$

$$= \prod_R \prod_K \left( \prod_{q \in K \setminus R} \beta_q \prod_{q \in K \cap R} (1 - \beta_q) \prod_{q \in R \setminus K} \eta_q \prod_{q \in R \cap \bar{K}} (1 - \eta_q) \right)^{M_{RK}} \cdot (\pi_K)^{M_{RK}} \quad (4)$$

and the log-likelihood becomes

$$\begin{aligned} \ell(\theta) = & \sum_R \sum_K M_{RK} \left( \sum_{q \in K \setminus R} \log \beta_q + \sum_{q \in K \cap R} \log(1 - \beta_q) + \sum_{q \in R \setminus K} \log \eta_q + \sum_{q \in \bar{R} \cap \bar{K}} \log(1 - \eta_q) \right) \\ & + \sum_R \sum_K M_{RK} \log \pi_K. \end{aligned} \quad (5)$$

## 1.2. Careless errors and lucky guesses

Let  $\mathcal{R}_q$  and  $\mathcal{R}_{\bar{q}}$  denote the subset of response patterns that contain and do not contain  $q$ , respectively. Similarly, let  $\mathcal{K}_q$  and  $\mathcal{K}_{\bar{q}}$  denote the subset of knowledge states that contain and do not contain  $q$ , respectively. Then the partial derivative of the log-likelihood with respect to  $\beta_q$  is

$$\frac{\partial \ell(\theta)}{\partial \beta_q} = \sum_R \sum_K \left( \sum_{q \in K \setminus R} \frac{M_{RK}}{\beta_q} - \sum_{q \in K \cap R} \frac{M_{RK}}{1 - \beta_q} \right) \quad (6)$$

$$= \sum_{R \in \mathcal{R}_{\bar{q}}} \sum_{K \in \mathcal{K}_q} \frac{M_{RK}}{\beta_q} - \sum_{R \in \mathcal{R}_q} \sum_{K \in \mathcal{K}_{\bar{q}}} \frac{M_{RK}}{1 - \beta_q} \quad (7)$$

$$= \sum_R \sum_{K \in \mathcal{K}_q} \frac{M_{RK}}{\beta_q} \cdot (1 - i) - \frac{M_{RK}}{1 - \beta_q} \cdot i, \quad (8)$$

where  $i = 1$  if  $R \in \mathcal{R}_q$ , and  $i = 0$  else. Setting the derivative to zero yields

$$\sum_R \sum_{K \in \mathcal{K}_q} \frac{M_{RK}(1 - i)(1 - \hat{\beta}_q) - M_{RK}i\hat{\beta}_q}{\hat{\beta}_q(1 - \hat{\beta}_q)} = 0 \quad (9)$$

$$\sum_R \sum_{K \in \mathcal{K}_q} M_{RK} - M_{RK}\hat{\beta}_q - M_{RK}i + \cancel{M_{RK}i\hat{\beta}_q} - \cancel{M_{RK}i\hat{\beta}_q} = 0 \quad (10)$$

$$\sum_R \sum_{K \in \mathcal{K}_q} M_{RK}(1 - i) = \sum_R \sum_{K \in \mathcal{K}_q} M_{RK}\hat{\beta}_q \quad (11)$$

$$\sum_{R \in \mathcal{R}_{\bar{q}}} \sum_{K \in \mathcal{K}_q} M_{RK} = \hat{\beta}_q \sum_R \sum_{K \in \mathcal{K}_q} M_{RK} \quad (12)$$

$$\hat{\beta}_q = \frac{\sum_{R \in \mathcal{R}_{\bar{q}}} \sum_{K \in \mathcal{K}_q} M_{RK}}{\sum_R \sum_{K \in \mathcal{K}_q} M_{RK}}. \quad (13)$$

The partial derivative of the log-likelihood with respect to  $\eta_q$  is

$$\frac{\partial \ell(\theta)}{\partial \eta_q} = \sum_R \sum_K \left( \sum_{q \in R \setminus K} \frac{M_{RK}}{\eta_q} - \sum_{q \in \bar{R} \cap \bar{K}} \frac{M_{RK}}{1 - \eta_q} \right) \quad (14)$$

$$= \sum_{R \in \mathcal{R}_q} \sum_{K \in \mathcal{K}_{\bar{q}}} \frac{M_{RK}}{\eta_q} - \sum_{R \in \mathcal{R}_{\bar{q}}} \sum_{K \in \mathcal{K}_q} \frac{M_{RK}}{1 - \eta_q} \quad (15)$$

$$= \sum_R \sum_{K \in \mathcal{K}_{\bar{q}}} \frac{M_{RK}}{\eta_q} \cdot i - \frac{M_{RK}}{1 - \eta_q} \cdot (1 - i), \quad (16)$$

where, as above,  $i = 1$  if  $R \in \mathcal{R}_q$ , and  $i = 0$  else. Setting the derivative to zero yields

$$\sum_R \sum_{K \in \mathcal{K}_{\bar{q}}} \frac{M_{RK}i(1 - \hat{\eta}_q) - M_{RK}(1 - i)\hat{\eta}_q}{\hat{\eta}_q(1 - \hat{\eta}_q)} = 0 \quad (17)$$

$$\sum_R \sum_{K \in \mathcal{K}_{\bar{q}}} M_{RK}i - \cancel{M_{RK}i\hat{\eta}_q} - M_{RK}\hat{\eta}_q + \cancel{M_{RK}i\hat{\eta}_q} = 0 \quad (18)$$

$$\sum_R \sum_{K \in \mathcal{K}_{\bar{q}}} M_{RK}i = \sum_R \sum_{K \in \mathcal{K}_{\bar{q}}} M_{RK}\hat{\eta}_q \quad (19)$$

$$\sum_{R \in \mathcal{R}_q} \sum_{K \in \mathcal{K}_{\bar{q}}} M_{RK} = \hat{\eta}_q \sum_R \sum_{K \in \mathcal{K}_{\bar{q}}} M_{RK} \quad (20)$$

$$\hat{\eta}_q = \frac{\sum_{R \in \mathcal{R}_q} \sum_{K \in \mathcal{K}_{\bar{q}}} M_{RK}}{\sum_R \sum_{K \in \mathcal{K}_{\bar{q}}} M_{RK}}. \quad (21)$$

### 1.3. State probabilities

Including the constraint  $\sum_K \pi_K = 1$  into the log-likelihood using the Lagrange multiplier  $\lambda$  leads to the function

$$\ell(\pi, \lambda) = \sum_R \sum_K M_{RK} \log \pi_K + \lambda \left( \sum_K \pi_K - 1 \right) \quad (22)$$

to be maximized with respect to  $\pi_K$  and  $\lambda$ . Thus,

$$\frac{\partial \ell(\pi, \lambda)}{\partial \pi_K} = \sum_R \frac{M_{RK}}{\pi_K} + \lambda, \quad (23)$$

$$\frac{\partial \ell(\pi, \lambda)}{\partial \lambda} = \sum_K \pi_K - 1. \quad (24)$$

Setting (23) to zero and solving for  $\pi_K$  gives

$$\pi_K = -\frac{\sum_R M_{RK}}{\lambda}. \quad (25)$$

Setting (24) to zero, substituting  $\pi_K$  by (25), and solving for  $\lambda$  gives

$$\hat{\lambda} = -\sum_R \sum_K M_{RK} = -N, \quad (26)$$

which, when substituted back into (25), leads to

$$\hat{\pi}_K = \frac{\sum_R M_{RK}}{N}. \quad (27)$$

#### 1.4. Expectation maximization

The expectation of the unobservable frequencies  $M_{RK}$  is

$$E(M_{RK}) = N_R \cdot P(K|R) \quad (28)$$

$$= N_R \cdot \frac{P(R|K)P(K)}{P(R)} \quad (29)$$

$$= N_R \cdot \frac{P(R|K)P(K)}{\sum_K P(R|K)P(K)}, \quad (30)$$

where, in each iteration,  $P(R|K)$  and  $P(K)$  are calculated from the current values of  $\hat{\beta}_q$ ,  $\hat{\eta}_q$ , and  $\hat{\pi}_K$ . These values are iteratively updated when substituting the  $M_{RK}$  by their expectations in (13), (21), and (27).

#### 1.5. Minimum-discrepancy maximum likelihood

Assuming that  $K$  is the underlying knowledge state for a response pattern  $R$ , the distance

$$d(R, K) = |(R \setminus K) \cup (K \setminus R)| \quad (31)$$

contains the number of response errors in  $R$ . Minimizing the number of response errors, a state is assigned to  $R$  if its distance takes on the smallest possible value,

$$i_{RK} = \begin{cases} 1 & \text{if } d(R, K) = \min_K d(R, K), \\ 0 & \text{else.} \end{cases} \quad (32)$$

Under this assumption of minimum discrepancy, the conditional probability  $P(K|R)$  is estimated by  $i_{RK}/i_{R+}$ , where  $i_{R+} = \sum_K i_{RK}$ . Consequently,

$$\hat{P}(R, K) = \hat{P}(K|R) \cdot \hat{P}(R) = \frac{i_{RK}}{i_{R+}} \cdot \frac{N_R}{N}. \quad (33)$$

This leads to the minimum-discrepancy estimators

$$\hat{\pi}_K = \hat{P}(K) = \sum_R \hat{P}(R, K) = \sum_R \frac{i_{RK}}{i_{R+}} \cdot \frac{N_R}{N} \quad (34)$$

$$\hat{\beta}_q = \hat{P}(\mathcal{R}_{\bar{q}}|\mathcal{K}_q) = \frac{\hat{P}(\mathcal{R}_{\bar{q}}, \mathcal{K}_q)}{\hat{P}(\mathcal{K}_q)} = \frac{\sum_{R \in \mathcal{R}_{\bar{q}}} \sum_{K \in \mathcal{K}_q} \hat{P}(R, K)}{\sum_{K \in \mathcal{K}_q} \hat{P}(K)} = \frac{\sum_{R \in \mathcal{R}_{\bar{q}}} \sum_{K \in \mathcal{K}_q} \frac{i_{RK}}{i_{R+}} \cdot N_R}{\sum_R \sum_{K \in \mathcal{K}_q} \frac{i_{RK}}{i_{R+}} \cdot N_R} \quad (35)$$

$$\hat{\eta}_q = \hat{P}(\mathcal{R}_q|\mathcal{K}_{\bar{q}}) = \frac{\hat{P}(\mathcal{R}_q, \mathcal{K}_{\bar{q}})}{\hat{P}(\mathcal{K}_{\bar{q}})} = \frac{\sum_{R \in \mathcal{R}_q} \sum_{K \in \mathcal{K}_{\bar{q}}} \hat{P}(R, K)}{\sum_{K \in \mathcal{K}_{\bar{q}}} \hat{P}(K)} = \frac{\sum_{R \in \mathcal{R}_q} \sum_{K \in \mathcal{K}_{\bar{q}}} \frac{i_{RK}}{i_{R+}} \cdot N_R}{\sum_R \sum_{K \in \mathcal{K}_{\bar{q}}} \frac{i_{RK}}{i_{R+}} \cdot N_R}. \quad (36)$$

An estimator that combines minimum discrepancy and maximum likelihood is obtained by augmenting the E step in (28) such that the expectation can only be non-zero under minimum discrepancy,

$$E(M_{RK}) = N_R \cdot \frac{i_{RK} \cdot P(K|R)}{\sum_K i_{RK} \cdot P(K|R)}. \quad (37)$$

Substituting the  $M_{RK}$  by this expectation in (13), (21), and (27) yields the minimum-discrepancy maximum likelihood estimators.

## 2. The simple learning model

### 2.1. Likelihood and log-likelihood

The SLM constrains the state distribution  $P(K)$  by introducing item-specific solvability parameters  $g_q$ . Thus, the parameter vector  $\theta = (\beta, \eta, g)$  consists of (vectors of) careless error, lucky guess, and solvability probabilities. With the unobservable frequency  $M_{RK}$  as defined above, the likelihood becomes

$$L(\theta) = \prod_R \prod_K (P(R | K) \cdot P(K))^{M_{RK}} \quad (38)$$

$$= \prod_R \prod_K P(R | K)^{M_{RK}} \cdot \left( \prod_{q \in K} g_q \prod_{q \in K^{\mathcal{O}}} (1 - g_q) \right)^{M_{RK}}, \quad (39)$$

where

$$K^{\mathcal{O}} = \{q \notin K \mid K \cup \{q\} \in \mathcal{K}\} \quad (40)$$

is the set of items that can be learned from  $K$ , called the outer fringe of  $K$ . According to the SLM,  $P(K)$  is the product of the probabilities of mastering all items in  $K$ ,  $g_q$ , and not mastering any items accessible from  $K$ ,  $1 - g_q$ . The log-likelihood then becomes

$$\begin{aligned} \ell(\theta) &= \sum_R \sum_K M_{RK} \log P(R | K) \\ &\quad + \sum_R \sum_K M_{RK} \left( \sum_{q \in K} \log g_q + \sum_{q \in K^{\mathcal{O}}} \log(1 - g_q) \right). \end{aligned} \quad (41)$$

### 2.2. Careless errors and lucky guesses

The estimators for careless error  $\beta$  and lucky guess  $\eta$  parameters in the SLM are the same as for the BLIM.

### 2.3. Solvability parameters

The partial derivative of the log-likelihood with respect to  $g_q$  is

$$\frac{\partial \ell(\theta)}{\partial g_q} = \sum_R \sum_K \left( \sum_{q \in K} \frac{M_{RK}}{g_q} - \sum_{q \in K^{\mathcal{O}}} \frac{M_{RK}}{1 - g_q} \right) \quad (42)$$

$$= \sum_R \sum_{K \in \mathcal{K}_q} \frac{M_{RK}}{g_q} - \sum_R \sum_{K \in \mathcal{K}_q^{\mathcal{O}}} \frac{M_{RK}}{1 - g_q} \quad (43)$$

$$= \sum_R \sum_K \frac{M_{RK}}{g_q} \cdot i - \frac{M_{RK}}{1 - g_q} \cdot j, \quad (44)$$

where

$$i = \begin{cases} 1 & \text{if } q \in K \\ 0 & \text{if } q \notin K \end{cases}, \quad j = \begin{cases} 1 & \text{if } q \in K^{\mathcal{O}} \\ 0 & \text{if } q \notin K^{\mathcal{O}} \end{cases}, \quad (45)$$

and  $\mathcal{K}_q^{\mathcal{O}}$  is the subset of states whose outer fringe contains  $q$ . Setting the derivative to zero yields

$$\sum_R \sum_K \frac{M_{RK}i(1 - \hat{g}_q) - M_{RK}j\hat{g}_q}{\hat{g}_q(1 - \hat{g}_q)} = 0 \quad (46)$$

$$\sum_R \sum_K M_{RK}i - M_{RK}i\hat{g}_q - M_{RK}j\hat{g}_q = 0 \quad (47)$$

$$\sum_R \sum_K M_{RK}i = \sum_R \sum_K \hat{g}_q(M_{RK}i + M_{RK}j) \quad (48)$$

$$\sum_R \sum_{K \in \mathcal{K}_q} M_{RK} = \hat{g}_q \left( \sum_R \sum_{K \in \mathcal{K}_q} M_{RK} + \sum_R \sum_{K \in \mathcal{K}_q^{\mathcal{O}}} M_{RK} \right) \quad (49)$$

$$\hat{g}_q = \frac{\sum_R \sum_{K \in \mathcal{K}_q} M_{RK}}{\sum_R \sum_{K \in \mathcal{K}_q} M_{RK} + \sum_R \sum_{K \in \mathcal{K}_q^{\mathcal{O}}} M_{RK}}. \quad (50)$$

## 2.4. Expectation maximization

The E step has the same form as for the BLIM. In each iteration,  $P(R|K)$  and  $P(K)$  are calculated from the current values of  $\hat{\beta}_q$ ,  $\hat{\eta}_q$ , and  $\hat{g}_q$ .

## 2.5. Minimum-discrepancy maximum likelihood

The minimum-discrepancy estimators  $\hat{\beta}_q$  and  $\hat{\eta}_q$  are the same as for the BLIM. For the solvability parameters,

$$\hat{g}_q = \hat{P}(\mathcal{K}_q | \mathcal{K}_q \cup \mathcal{K}_q^{\mathcal{O}}) = \frac{\hat{P}(\mathcal{K}_q, \mathcal{K}_q \cup \mathcal{K}_q^{\mathcal{O}})}{\hat{P}(\mathcal{K}_q \cup \mathcal{K}_q^{\mathcal{O}})} = \frac{\hat{P}(\mathcal{K}_q)}{\hat{P}(\mathcal{K}_q \cup \mathcal{K}_q^{\mathcal{O}})} \quad (51)$$

$$= \frac{\sum_R \sum_{K \in \mathcal{K}_q} \hat{P}(R, K)}{\sum_R \sum_{K \in \mathcal{K}_q} \hat{P}(R, K) + \sum_R \sum_{K \in \mathcal{K}_q^{\mathcal{O}}} \hat{P}(R, K)} \quad (52)$$

$$= \frac{\sum_R \sum_{K \in \mathcal{K}_q} \frac{i_{RK}}{i_{R+}} \cdot N_R}{\sum_R \sum_{K \in \mathcal{K}_q} \frac{i_{RK}}{i_{R+}} \cdot N_R + \sum_R \sum_{K \in \mathcal{K}_q^{\mathcal{O}}} \frac{i_{RK}}{i_{R+}} \cdot N_R}. \quad (53)$$

Minimum-discrepancy maximum likelihood estimators for  $\beta$ ,  $\eta$ , and  $g$  are obtained from augmenting the E step as in (37).

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## References

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